

# Waterproof DS18B20 Digital Temperature Sensor (SKU:DFR0198)



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## Introduction

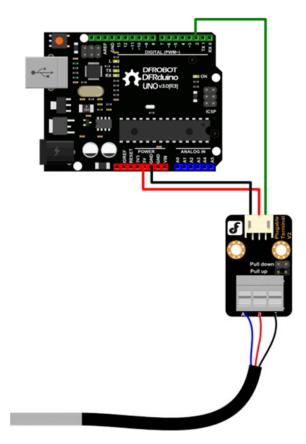
This is a waterproofed version of the **DS18B20** Arduino **Temperature sensor**. Handy for when you need to measure something far away, or in wet conditions. While the sensor is good up to 125°C the cable is jacketed in PVC so we suggest keeping it under 100°C. Because they are digital, you don't get any signal degradation even over long distances! The DS18B20 provides 9 to 12-bit (configurable) temperature readings over a 1-Wire interface, so that only one wire (and ground) needs to be connected from a central microprocessor.Usable with 3.0-5.5V systems. Because each DS18B20 contains a unique silicon serial number, multiple DS18B20s can exist on the same 1-Wire bus. This allows for placing temperature sensors in many different places. Applications where this feature is useful include HVAC environmental controls, sensing temperatures inside buildings, equipment or machinery, and process monitoring and control.

#### Specification

- Usable with 3.0V to 5.5V power/data
- ±0.5°C Accuracy from -10°C to +85°C
- Usable temperature range: -55 to 125°C (-67°F to +257°F)
- 9 to 12 bit selectable resolution
- Uses 1-Wire interface- requires only one digital pin for communication
- Unique 64 bit ID burned into chip
- Multiple sensors can share one pin
- Temperature-limit alarm system
- Query time is less than 750ms
- 3 wires interface: Red wire - VCC Black wire - GND Yellow wire - DATA
- Stainless steel tube 6mm diameter by 35mm long
- Cable diameter: 4mm
- Length: 90cm

#### Sensor Connection

This sensor requires a 4.7K Ohm resistor between the voltage and Signal pin. as seen in the picture below. Optionally you can use a Plugable Terminal sensor adapter to help in making this connection secure.



## Sample Code

Sample code for Arduino 1.0 and above.

```
#include <OneWire.h>
int DS18S20_Pin = 2; //DS18S20 Signal pin on digital 2
//Temperature chip i/o
OneWire ds(DS18S20_Pin); // on digital pin 2
void setup(void) {
  Serial.begin(9600);
}
void loop(void) {
  float temperature = getTemp();
  Serial.println(temperature);
 delay(100); //just here to slow down the output so it is easier to read
}
float getTemp(){
  //returns the temperature from one DS18S20 in DEG Celsius
 byte data[12];
 byte addr[8];
  if ( !ds.search(addr)) {
      //no more sensors on chain, reset search
      ds.reset_search();
      return -1000;
  }
```

```
if ( OneWire::crc8( addr, 7) != addr[7]) {
    Serial.println("CRC is not valid!");
   return -1000;
}
if ( addr[0] != 0x10 && addr[0] != 0x28) {
    Serial.print("Device is not recognized");
   return -1000;
}
ds.reset();
ds.select(addr);
ds.write(0x44,1); // start conversion, with parasite power on at the end
byte present = ds.reset();
ds.select(addr);
ds.write(0xBE); // Read Scratchpad
for (int i = 0; i < 9; i++) { // we need 9 bytes
 data[i] = ds.read();
}
ds.reset_search();
byte MSB = data[1];
byte LSB = data[0];
float tempRead = ((MSB << 8) | LSB); //using two's compliment</pre>
float TemperatureSum = tempRead / 16;
return TemperatureSum;
```

## Additional documentation

}

#### ZIP file With sample codes, datasheet, and required libraries.

http://www.dfrobot.com/image/data/DFR0198/DFRobot%20DFR0198.zip